## Power Monitor IC with Analog Output

## FEATURES

- Accurate *TruePower*<sup>TM</sup> monitor
  - 2.5% static accuracy
  - Minimizes dynamic errors
- Minimizes power dissipation
  - 5mV 150mV full scale current range
- Versatile
  - Monitors power or current
  - Single buck or multiphase converters
  - Inductor DCR or resistive shunt sensing
- Simple add-on to existing converters
- 10 pin 3x3 DFN lead free package
- RoHS compliant

### DESCRIPTION

The IR3721 is a versatile power or current monitor IC for low-voltage DC-DC converters. The IR3721 monitors the inductor current in buck or multiphase converters using either a current sensing resistor or the inductor's winding resistance (DCR). The output (DI) is a pulse code modulated signal whose duty ratio is proportional to the inductor current. An analog voltage that is proportional to power is realized by connecting  $V_{\rm K}$  to  $V_{\rm O}$  and connecting an RC filter to DI.

The IR3721 uses Patent Pending *TruePower*<sup>™</sup> technology to accurately capture highly dynamic power waveforms typical of microprocessor loads.

## **TYPICAL APPLICATION CIRCUIT**



## **ORDERING INFORMATION**

Device	Package	Order Quantity
IR3721MTRPBF	10 lead DFN (3x3 mm body)	3000 piece reel
* IR3721MPBF	10 lead DFN (3x3 mm body)	121 piece tube

\* Samples only

## **ABSOLUTE MAXIMUM RATINGS**

Absolute Maximum Ratings (Referenced to G	ND)
VDD:	.3.9V
All other Analog and Digital pins	.3.9V

Operating Junction Temperature10°C to 150°C
Storage Temperature Range65°C to 150°C
ESD Rating
MSL RatingLevel 2
Reflow Temperature 260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications are not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **ELECTRICAL SPECIFICATIONS**

Unless otherwise specified, these specifications apply: VDD =  $3.3V \pm 5\%$ ,  $0^{\circ}C \le T_{J} \le 125^{\circ}C$ ,  $0.5 \le Vo \le 1.8$  V, and operation in the typical application circuit. See notes following table.

PARAMETER	TEST CONDITION	MIN	TYP	MAX	UNIT
BIAS SUPPLY	_	_	_		_
VDD Turn-on Threshold, VDD <sub>UP</sub>				3.10	V
VDD Turn-off Threshold, VDD <sub>DN</sub>		2.4			V
VDD UVLO Hysteresis	DI output low when off	75			mV
VDD Operating Current, ICC			350	450	μA
VOLTAGE REFERENCE	_	_	_		_
V <sub>RT</sub> Voltage	R <sub>T</sub> = 25.5k Ω	1.452	1.493	1.535	V
R <sub>T</sub> resistance range	Note 1		25.5		kΩ
ΔΣ CONVERTER					
Vo common mode range		0.5		1.8	V
Duty Ratio Accuracy	$V_{DCR}$ =20 mV, $V_{O}$ =1V, R <sub>T</sub> =25.5kΩ, R <sub>CS1</sub> +R <sub>CS2</sub> =600 Ω T <sub>i</sub> =65°C, Note 1			2.5	%
Duty Ratio Accuracy	$V_{DCR}$ =20 mV, V <sub>0</sub> =1V, R <sub>T</sub> =25.5kΩ, R <sub>CS1</sub> +R <sub>CS2</sub> =600 Ω, Note 1			4	%
Sampling frequency, f <sub>CLK</sub>		435	512	589	kHz
Comparator Offset		-0.5		+0.5	mV
CS pin input current, I <sub>CS</sub>	DI output low	-250		+250	nA
DIGITAL OUTPUT					
VK pin voltage range		0.5		1.8	V
DI source resistance		1250	2000	3000	Ω

### NOTES:

1. Guaranteed by design

## **BLOCK DIAGRAM**



### **IC PIN DESCRIPTION**

NAME	NUMBER	I/O LEVEL	DESCRIPTION	
VCS	1	Analog	Current sensing input, connect through resistor to sensing node	
VO	2	Analog	Current sensing reference connect to output voltage	
VRT	3	Analog	$R_T$ thermistor network from this pin to GND programs thermal monitor	
GND	4		Bias return and signal reference	
VDD	5	3.3V	IC bias supply	
GND	6		Connect to pin 4	
GND	7		Connect to pin 4	
DI	8	Analog	Power Monitor output; connect to output filter	
VK	9	1.8V	Connect to fixed voltage or VO, multiplied by DI to become analog output	
VDD	10	3.3V	Connect to pin 5	
BASE PAD			Connect to pin 4	

## **IC PIN FUNCTIONS**

### **VDD PINS**

These pins provide operational bias current to circuits internal to the IR3721. Bypass them with a high quality ceramic capacitor to the GND pins.

### **GND PINS**

These pins return operational bias current to system ground. VO is measured with respect to GND. The GND pin sinks reference current established by the external resistor  $R_T$ .

### **VO PIN**

Since this pin measures DCR voltage drop it is critical that it be Kelvin connected to the buck inductor output. Power accuracy may be degraded if the voltage at this pin is below  $VO_{min}$ .

### VCS PIN

A switched current source internal to the IR3721 maintains the average voltage of this pin equal to the voltage of the VO pin. The average current into this pin is therefore proportional to buck inductor current.

### **VRT PIN**

A voltage reference internal to the IR3721 drives the  $V_{RT}$  pin while the pin current is monitored and used to set the amplitude of the current monitor switched current source  $I_{REF}$ . Connect this pin to GND through a precision resistor network  $R_T$ . This network may include provision for canceling the positive temperature coefficient of the buck inductor's DC resistance (DCR).

### VK PIN

The voltage of the VK pin is used to modulate the amplitude of the DI pin. This is one of the terms used to determine the product of the multiplier output. If VK is connected to a fixed voltage then the output of the multiplier is proportional to current. If VK is connected to the buck converter output voltage then the output of the DI driven RC filter is proportional to power.

### DI PIN

The DI pin output has a duty ratio proportional to the current into VCS, and an amplitude equal to the voltage at the VK pin. The DI pin is intended to drive an external low pass filter. The output of this filter is the product of the current and voltage terms.

### FUNCTIONAL DESCRIPTION

Please refer to the Functional Description Diagram below. Power flow from the buck converter inductor is the product of output voltage times the current  $I_L$  flowing through the inductor.

Power is measured with the aid of International Rectifier's proprietary TruePower™ circuit. Current is converted to a duty ratio that appears at the DI pin. The duty ratio of the DI pin is

$$\mathsf{DI}_{\mathsf{DUTYRATIO}} = \frac{\mathsf{I}_{\mathsf{L}} \cdot \mathsf{DCR}}{(\mathsf{R}_{\mathsf{CS1}} + \mathsf{R}_{\mathsf{CS2}})} \cdot \frac{\mathsf{R}_{\mathsf{T}}}{\mathsf{V}_{\mathsf{RT}}}$$

Equation 1

The full-scale current that can be measured corresponds to a duty ratio of one.

The amplitude of the DI pin is the voltage appearing at pin VK. If a fixed voltage is applied to VK then the output of the RC filter driven by DI will be proportional to inductor current  $I_L$ .

If VO is applied to  $V_K$  as shown in the figure then the output of the DI driven RC network will be proportional to power. The full-scale voltage that can be measured is established on the chip to be 1.8V.

The full scale power  $P_{FS}$  that can be measured is the product of full-scale voltage and full scale current.



Figure 1 Functional Description Diagram

## THERMAL COMPENSATION FOR INDUCTOR DCR CURRENT SENSING

The positive temperature coefficient of the inductor DCR can be compensated if  $R_T$  varies inversely proportional to the DCR. DCR of a copper coil, as a function of temperature, is approximated by

 $DCR(T) = DCR(T_R) \cdot (1 + (T - T_R) \cdot TCR_{Cu})$ 

#### Equation 2

 $T_R$  is some reference temperature, usually 25 °C, and TCR<sub>Cu</sub> is the resistive temperature coefficient of copper, usually assumed to be 0.39 %/°C near room temperature. Note that equation 2 is linearly increasing with temperature and has an offset of DCR( $T_R$ ) at the reference temperature. If  $R_T$  incorporates a negative temperature coefficient thermistor then temperature effects of DCR can be minimized. Consider a circuit of two resistors and a thermistor as shown below.



**Equation 3** 

where  $R_{th}(T)$  is the thermistor resistance at some temperature T,  $R_{th}(T_0)$  is the thermistor resistance at the reference temperature  $T_0$ , and  $\beta$  is the material constant provided by the thermistor manufacturer. Kelvin degrees are used in the exponential term of equation 3. If  $R_S$  is large and  $R_P$  is small, the curvature of the equivalent network resistance can be reduced from the curvature of the thermistor alone. Although the exponential equation 3 can never compensate linear equation 2 at all temperatures, a spreadsheet can be constructed to minimize error over the temperature interval of interest. The equivalent resistance  $R_T$  of the network shown as a function of temperature is

$$R_{T}(T) = R_{s} + \frac{1}{\frac{1}{R_{n}} + \frac{1}{R_{th}(T)}}$$



using  $R_{th}(T)$  from equation 3. Equation 2 may be rewritten as a new function of temperature using equations 2 and 4 as follows:

$$I_{FS}(T) = \frac{V_{RT}}{R_{T}(T)} \cdot \frac{\left(R_{CS1} + R_{CS2}\right)}{DCR(T)}$$

**Equation 5** 

With Rs and Rp as additional free variables, use a spreadsheet to solve equation 5 for the desired full scale current while minimizing the  $I_{FS}(T)$  variation over temperature.



Figure 2 R<sub>T</sub> Network

If Rth is an NTC thermistor then the value of the network will decrease as temperature increases. Unfortunately, most thermistors exhibit far more variation with temperature than copper wire. One equation used to model thermistors is International

## **TYPICAL 2-PHASE DCR SENSING APPLICATION**

The IR3721 is capable of monitoring power in a multiphase converter. A Two Phase DCR Sensing Circuit is shown below. The voltage output of any phase is equal to that of any and every other phase because they are electrically connected and monitored at VO as before.

Output current is the sum of the two inductor currents  $(I_{L1} + I_{L2})$ . Superposition is used to derive the transfer function for multiphase sensing. The voltage on  $R_{CS2}$  due to  $I_{L1}$  is

$$I_{L1} \cdot DCR_1 \cdot \frac{(R_{CS2} || R_{CS3})}{R_{CS1} + (R_{CS2} || R_{CS3})}$$

Likewise, the voltage on RCS2 due to IL2 is

$$I_{L2} \cdot DCR_2 \cdot \frac{(R_{CS2} || R_{CS1})}{R_{CS3} + (R_{CS2} || R_{CS1})}$$

The current through  $R_{CS2}$  due to both inductor currents is  $I_{CS}$ . From the two equations above

$$I_{CS} = \frac{I_{L1}DCR_{1}R_{CS3} + I_{L2}DCR_{2}R_{CS1}}{R_{CS1}R_{CS2} + R_{CS1}R_{CS3} + R_{CS2}R_{CS3}}$$

The duty ratio of DI is

$$DI_{DUTYRATIO} = \frac{I_{CS} \cdot R_T}{V_{REF}}$$

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If DCR1=DCR2, and RCS1=RCS3, then  $I_{\text{CS}}$  can be simplified to

$$I_{\rm CS} = \frac{(I_{L1} + I_{L2}) \cdot DCR_1}{R_{\rm CS1} + 2R_{\rm CS2}}$$

and the DI duty ratio simplifies to

$$\mathsf{DI}_{\mathsf{DUTYRATIO}} = \frac{(\mathsf{I}_{\mathsf{L1}} + \mathsf{I}_{\mathsf{L2}}) \cdot \mathsf{DCR} \cdot \mathsf{R}_{\mathsf{T}}}{(\mathsf{R}_{\mathsf{CS1}} + 2\mathsf{R}_{\mathsf{CS2}}) \cdot \mathsf{V}_{\mathsf{RT}}}$$

Full scale current occurs when DI duty ratio becomes one.



## **RESISTOR SENSING APPLICATION**

The Resistor Sensing Circuit shown below is an example of resistive current sensing. Because the voltage on the shunt resistor is directly proportional to the current I<sub>L</sub> through the inductor,  $R_{CS2}$  and  $C_{CS2}$  do not need to match the L / DCR time constant.

Because the value of the shunt resistance does not change with temperature as the inductor DCR does,  $R_T$  can be a fixed resistor.



Figure 4 Resistor Sensing Circuit

## **COMPONENT SELECTION GUIDELINES**

Use a 0.1  $\mu$ F, 6.3V, X7R ceramic bypass capacitor from VDD to GND and from VK to GND. Filter the DI output with an RC filter to give a stable analog representation of the current or power. Some of the DI source resistance of this filter is internal to the IR3721 and specified in the electrical specifications table. Add twenty thousand to fifty thousand additional ohms externally to minimize resistance variation. As the DI source resistance increases beyond these guidelines, the voltage measurement error caused by non-ideal voltmeter conductance will increase.

Select a filter capacitor that limits 512 kHz sampling frequency ripple to an acceptable value. Sampling frequency ripple will appear as an error, but can be reduced 20 dB for each decade that the filter corner frequency is below 512 kHz. Select a capacitor value that achieves the desired balance between low sampling frequency ripple and adequate bandwidth.

### **Resistor current sensing**

For resistor current sensing select a precision resistor for  $R_T$  inside the  $R_T$  resistance range limits specified in the Electrical Specifications table, such as  $25.5k\Omega$  and 1% tolerance.

Next, select a shunt resistor that will provide the most current sensing voltage while also considering the allowable power dissipation limitations. The DI output will saturate to the VK voltage when full scale current I<sub>FS</sub> flows through this shunt. Recommended maximum current sensing voltage range is 5 to 150 mV. Maximum sensing voltages less than 5 mV will cause comparator input offset voltage errors to dominate, and voltages larger than 150 mV will cause comparator leakage current, I<sub>CS</sub>, errors to dominate. Select  $R_{CS2}$  to be the next higher standard value resistor from ( $R_{SHUNT} \cdot I_{FS} \cdot R_T$ ) /  $V_{RT}$  in order to accommodate full scale current  $I_{FS}$ .

Bypass VCS to VO with capacitor  $C_{CS2}$ . The value of this capacitor limits the bandwidth, but is required because it is the integrator of the delta sigma modulator. Consider selecting the value of  $C_{CS2}$  to place a filter corner frequency at 5 kHz, which will reduce sampling ripple by 40 dB.

### **DCR current sensing**

Select an  $R_{T}$  network resistance between  $20k\Omega$  and  $45.3k\Omega.$  Consider the  $R_{T}$  network of Figure 5 for DCR current sensing.



### Figure 5 R<sub>T</sub> network

The resistance of the network above at 25°C,  $R_T(25)$ , is 37.58k $\Omega$ . Over temperature  $R_T(T)$  is multiplied by copper resistance, DCR(25)·(1+(T-25)·0.0039), divided by (DCR(25)·( $R_T(25)$ ) to normalize the results, and plotted as nominal error in Figure 6.



### Figure 6 Nominal error vs. Temperature

Note that the error due to temperature compensation at 25°C is zero, assuming ideal  $R_T$  components. At other temperatures the results are over or under reported by the factor in percent indicated. Proceed to calculate  $R_{SUM}$ , defined as the sum of  $R_{CS1}$  plus  $R_{CS2}$ , as follows.

$$R_{SUM} = I_{FS} \cdot DCR(25) \cdot R_T(25) / V_{RT}$$

Again,  $I_{FS}$  is full scale current and  $V_{RT}$  is the reference voltage establishing the current in  $R_T$ . Estimate the capacitance  $C_{CS1}$  with the following equation.

$$C_{CS1} > \frac{4 \cdot L}{DCR(25) \cdot R_{SUM}}$$

Choose a standard capacitor value larger than indicated by the right hand side of the inequality above.

Calculate the equivalent resistance R<sub>eq</sub>.

$$R_{eq} = L / (DCR(25) \cdot C_{CS1})$$

We now have two equations,  $R_{SUM} = R_{CS1} + R_{CS2}$  and Req =  $(R_{CS1} \cdot R_{CS2}) / (R_{CS1} + R_{CS2})$ . Calculate  $R_{CS1}$  and  $R_{CS2}$  using the following two equations.

$$R_{CS1} = R_{SUM} \cdot \left( \frac{1 + \sqrt{1 - 4 \cdot \frac{R_{eq}}{R_{SUM}}}}{2} \right) \text{ and}$$
$$R_{CS2} = R_{SUM} \cdot \left( \frac{1 - \sqrt{1 - 4 \cdot \frac{R_{eq}}{R_{SUM}}}}{2} \right)$$

Use the next higher standard 1% value than indicated in the equations above. This will insure that full scale current can be measured.

Bypass VCS to VO with capacitor  $C_{CS2}$ . The value of this capacitor limits the bandwidth, but is required because it is the integrator of the delta sigma modulator. Consider selecting the value of  $C_{CS2}$  to place a filter corner frequency at 5 kHz, which will reduce sampling ripple by 40 dB.

## LAYOUT GUIDELINES

Refer to figures 7 through 11 for guidance laying out the IR3721. These guidelines also apply to resistive current sensing. The following guidelines will minimize sources of noise and error, which is required because millivolt level signals correspond to amps of inductor current.

- 1. Place the capacitor Ccs2 close to the VO and VCS pins of the IR3721. Treat VO and VCS as a differential signal pair back to the IC as shown in the elliptical area designated #1 of figure 8.
- 2. Sense the inductor (or shunt) Kelvin style at its terminals. Route the leads back as a differential pair. Refer to area #2 of figure 8.
- 3. Route signal VOUT back to the IC VK pin on its own dedicated trace. Refer to area #3 of figure 8.
- 4. Place the thermistor near the inductor. Refer to area #4 of figure 8. Route the thermistor leads back to the rest of the network using differential traces. Mount the rest of the thermistor network consisting of Rs, Rp, and R1 close to the IC.

 Use an isolated dedicated ground plane connected only to components associated with the IR3721 that connect to GND as shown in figure 9. Connect this dedicated ground plane at one location only to the ground of the monitored voltage. The thermally relived via in figure eight illustrates this connection.

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- Bypass IC VDD pin 5 to GND pin 4 with a high quality 0.1 μF ceramic capacitor. Refer to area #6 of figure 8.
- Bypass the IC VK pin to GND with a high quality 0.1 μF ceramic capacitor. Refer to area #7 of figure 8.



### Figure 7 Example schematic

# International



Figure 8 Layer 1



Figure 9 Layer 2



Figure 10 Layer 3





International

## PCB PAD AND COMPONENT PLACEMENT

Figure 12 below shows suggested pad and component placement.



Figure 12 Pad placement

## SOLDER RESIST

Figure 13 below shows suggested solder resist placement.



All Dimensions in mm



PCB Copper

PCB Solder Resist

Figure 13 Solder resist

### **STENCIL DESIGN**

Figure 14 below shows a suggested stencil design.



Stencil Aperture All Dimensions in mm

Figure 14 Stencil design

### **PACKAGE INFORMATION**

### 3 X 3 MM 10L DFN LEAD FREE



SYMBOL	10 PIN 3X3 MM		
DESIGN	MIN	NOM	MAX
A	0.80	0.90	1.00
Al	0,00	0.02	0.05
A3	0.20 REF		
В	0,18	0,23	0,30
D	3.00 BSC		
D2	2.20		2.70
E	3,00 BSC		
E2	1.40		1.75
e	0.50 BSC		
L	0,30	0,40	0,50
R	0,09		

Data and specifications subject to change without notice. This product has been designed and qualified for the Consumer market. Qualification Standards can be found on IR's Web site.

International IR WORLD HEADQUARTERS: 233 Kansas St., El Segundo, California 90245, USA Tel: (310) 252-7105 TAC Fax: (310) 252-7903 Visit us at www.irf.com for sales contact information.