

DM9368 7-Segment Decoder/Driver/Latch with Constant Current Source Outputs

Truth Table

DM9368

| | | | INP | UTS | | | | | | 011 | PUT: | s | | | |
|----------------------------|-------------|-----------------------|-------------|------------------|------------------|-----------------------|-----------------------|-----------------------|--------------------|---------------------|-----------------------|-----------------------|-----------------------|------------------|-----------------|
| BINARY STATE | LE | RBI | A3 | A2 | A1 | A0 | a | b | с | d | e | f | g | RBO | DISPLAY |
| 0 0 1 | HLLL | * L H X | X L L | X L L L | X L L | X L H | ▼ L H L | L H H | — S L Н Н | TABI L H L | _Е — L H L | L H L | ► L L L | H L H H | STABLE BLANK |
| 2 3 4 5 | L L L | X X X X | L L L | L L H H | H H L | L H L | H H L H | H H L | L H H | H H L H | H L L | L L H | ннн | Н Н Н | ê îs e es |
| 6 7 8 9 10 | | X X X X X | L H H | H L L | H H L H | L H L H L | H H H H H | L H H H H | H H H H H | H L H L | H L H L | H L H H | H L H H H | H H H H | 67 0 0 0 0 |
| 11 12 13 14 15 | | X X X X X | нннн | LHHHH | H L H H | H L H L | L H L H H | L L H L | H L H L | H H H L | H H H H H | H H L H H | H L H H H | H H H H | no na To na m |
| Х | Х | х | х | Х | Х | Х | L | L | L | L | L | L | L | L** | BLANK |

*The RBI will blank the display only if a binary zero is stored in the latches.

*The RBO used as an input overrides all other input conditions.

H = HIGH Voltage Level

L = LOW Voltage Level

X = Immaterial



Functional Description

The DM9368 is a 7-segment decoder driver designed to drive 7-segment common cathode LED displays. The DM9368 drives any common cathode LED display rated at a nominal 20 mA at 1.7V per segment without need for current limiting resistors.

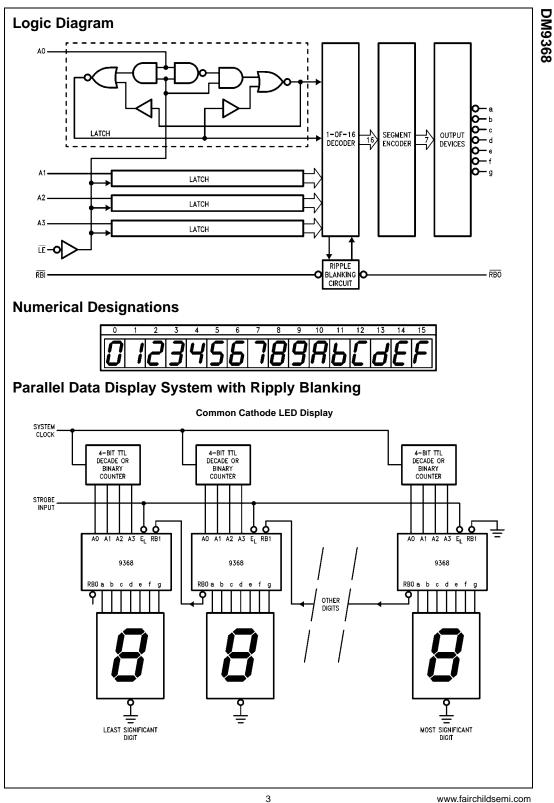
This device accepts a 4-bit binary code and produces output drive to the appropriate segments of the 7-segment display. It has a hexadecimal decode format which produces numeric codes "0" thru "9" and alpha codes "A" through "F" using upper and lower case fonts.

Latches on the four data inputs are controlled by an active LOW latch enable LE. When the LE is LOW, the state of the outputs is determined by the input data. When the LE goes HIGH, the last data present at the inputs is stored in the latches and the outputs remain stable. The LE pulse width necessary to accept and store data is typically 30 ns which allows data to be strobed into the DM9368 at normal TTL speeds. This feature means that data can be routed directly from high speed counters and frequency dividers into the display without slowing down the system clock or providing intermediate data storage.

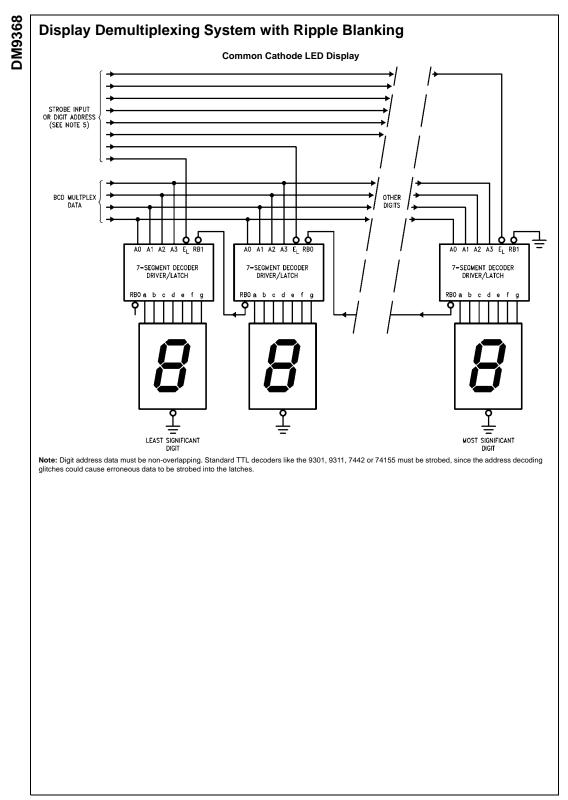
Another feature of the DM9368 is that the unit loading on the data inputs is very low (–100 μA Max) when the latch enable is HIGH. This allows DM9368s to be driven from an

MOS device in multiplex mode without the need for drivers on the data lines.

The DM9368 also has provision for automatic blanking of the leading and/or trailing edge zeros in a multidigit decimal number, resulting in an easily readable decimal display conforming to normal writing practice. In an eight digit mixed integer fraction decimal representation, using the automatic blanking capability, 0060.0300 would be displayed as 60.03. Leading edge zero suppression is obtained by connecting the Ripple Blanking Output (RBO) of a decoder to the Ripple Blanking Input (RBI) of the next lower stage device. The most significant decoder stage should have the RBI input grounded; and since suppression of the least significant integer zero in a number is not usually desired, the RBI input of this decoder stage should be left open. A similar procedure for the fractional part of a display will provide automatic suppression of trailing edge zeros. The RBO terminal of the decoder can be OR-tied with a modulating signal via an isolating buffer to achieve pulse duration intensity modulation. A suitable signal can be generated for this purpose by forming a variable frequency multivibrator with a cross coupled pair of TTL or DTL dates.



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Absolute Maximum Ratings(Note 1)

| Supply Voltage | 7V |
|--------------------------------------|---------------------------------|
| Input Voltage | 5.5V |
| Operating Free Air Temperature Range | $0^{\circ}C$ to $+70^{\circ}C$ |
| Storage Temperature Range | $-65^\circ C$ to $+150^\circ C$ |

Note 1: The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the Electrical Characteristics tables are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.

DM9368

Recommended Operating Conditions

t_{PHL}

LE to a-g

| V _{CC} | Symbol Paramet | | Min | Nom | Max | C | Units |
|---|--|---|--|------------|------------------------|---------------------------------------|---------------------------------|
| /CC | Supply Voltage | | 4.75 | 5 | 5.25 | 5 | V |
| / _{ін} | HIGH Level Input Voltage | | 2 | | | | V |
| / _{IL} | LOW Level Input Voltage | | | | 0.8 | | V |
| ОН | HIGH Level Output Curre | nt | | -80 | | | μΑ |
| OL | LOW Level Output Currer | t RBO | | | 3.2 | | mA |
| Γ _A | Free Air Operating Tempe | erature 0 | | | 70 | | °C |
| t _S (H) | Setup Time HIGH | | | | | | |
| A _n to LE | | 30 | | | | | ns |
| t _H (H) | Hold Time HIGH | | 0 | | | | |
| A_n to \overline{LE} | | | 0 | | | | ns |
| t _S (L) Setup Time LOW A _n to LE | | | 20 | | | n | |
| | | | 20 | | | | |
| t _H (L) Hold Time LOW | | | 0 | | | | - |
| | A _n to LE | | U | | | | ns |
| t _W (L) | LE Pulse Width LOW | | 45 | | | | ns |
| W(L) | | rrent -16 | | | -22 | 2 | mA |
| | Segment Output HIGH C | urrent | -16 | | | | |
| I _{OH} I _{OL} Electr Over recorr | Segment Output LOW Cu ical Characteristics mmended operating free air temperatur | rrent e range (unless other | -250 wise noted) | Min | 250 | | μA |
| loH loL Electr Over recorr Symbol | Segment Output LOW Cu rical Characteristics mended operating free air temperatur Parameter | rrent e range (unless other Cor | -250 wise noted) | Min | | Max | Unit |
| OH OL Over recom Symbol | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage | rrent e range (unless other Cor V _{CC} = Min, I ₁ = -1 | -250 wise noted) nditions 2 mA | Min | Тур | | |
| OH OL Over recom Symbol | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level | rrent e range (unless other $V_{CC} = Min, I_l = -1$ $V_{CC} = Min, I_{OH} =$ | -250 wise noted) nditions 2 mA | Min 2.4 | Тур | Max | Unit |
| OH OL OVer recorr Symbol VI VOH | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage | rrent e range (unless other Cor $V_{CC} = Min, I_1 = -1$ $V_{CC} = Min, I_{OH} =$ $V_{IL} = Max$ | -250 wise noted) nditions 2 mA Max, | | Typ (Note 2) | Max | Unit |
| OH OL OVer recorr Symbol VI VOH | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level | rrent e range (unless other Cor $V_{CC} = Min, I_1 = -1$ $V_{CC} = Min, I_{OH} =$ $V_{IL} = Max$ $V_{CC} = Min, I_{OL} = 1$ | -250 wise noted) nditions 2 mA Max, | | Typ (Note 2) | Max | Unit |
| OH OL Electr Over recorr Symbol VI VOH | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level Output Voltage | rrent e range (unless other Cor $V_{CC} = Min, I_1 = -1$ $V_{CC} = Min, I_{OH} =$ $V_{IL} = Max$ $V_{CC} = Min, I_{OL} = I$ $V_{IH} = Min$ | -250 wise noted) nditions 2 mA Max, Max, | | Typ (Note 2) 3.4 | Max -1.5 | Unit V V |
| он oL Electr Symbol V ₁ V _{0H} V _{0L} | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level | rrent e range (unless other Cor $V_{CC} = Min, I_1 = -1$ $V_{CC} = Min, I_{OH} =$ $V_{IL} = Max$ $V_{CC} = Min, I_{OL} = 1$ | -250 wise noted) nditions 2 mA Max, Max, 5.5V | | Typ (Note 2) 3.4 | Max -1.5 | Unit V V |
| он oL Electr Symbol V ₁ V _{0H} V _{0L} | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level Output Voltage Input Current @ Max Input Voltage | $\label{eq:constraint} \hline \begin{tabular}{ c c c c c } \hline & & & & & & & & & & & & & & & & & & $ | -250 wise noted) nditions 2 mA Max, Max, 5.5V 2.4V | | Typ (Note 2) 3.4 | Max -1.5 0.4 | Unit V V V |
| I _{OH} I _{OL} Electr Over recorr | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Current | $\label{eq:constraint} \begin{tabular}{ c c c c c } \hline rrent \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | -250 wise noted) nditions 2 mA Max, Max, 5.5V 2.4V 2.4V 0.4V 3) | | Typ (Note 2) 3.4 | Max -1.5 0.4 1 40 | Unit |
| I _{OH} IOL Electr Over recom Symbol V ₁ V _{0H} V _{0H} V _{0L} I ₁ I ₁ I ₁ I ₁ | Segment Output LOW Cu ical Characteristics mended operating free air temperatur Parameter Input Clamp Voltage HIGH Level Output Voltage LOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Current LOW Level Input Current | $\label{eq:constraint} \begin{tabular}{ c c c c c } \hline rrrent \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | -250 wise noted) nditions 2 mA Max, Max, 5.5V 2.4V 0.4V 3) uts OPEN, | 2.4 | Typ (Note 2) 3.4 | Max -1.5 0.4 1 40 -1.6 | Unit V V V MA MA |

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